Programmable Logic Controllers All-in-one type Compact PLC MICRO-EHV Series

ABSK

24VDC OUT 0V 0



39 CI

8 9 10 11 12 13 14 15 6 17 18 19 20 21 22 23

24 25 26 27 28 29 30 31

2 33 34 35 36 37 38 39 1 2 3 4 5 6 7 9 10 11 12 13 14 15 17 18 19 20 21 22 23

HITACHI

21 22 C18

RUN

STATUS

MICRO-EHV

MVH-A64DR

Double USB port for programming and USB flash device Ethernet communication port Easy connection with Hitachi inverters

> DW 8 9 10 11 12 13 14 15 DK 6 17 18 19 20 21 22 23 RUN 0 1 2 3 4 5 6 7 STATUS 2 8 9 10 11 12 13 14 15

> > 12 13 15 16 18 20 22 24 26 28 30

7 NC 9 11 NC 13 NC 15 NC 17 NC 19 NC C11 8 10 C12 12 C13 14 C14 16 C15 18 C16 1

MICRO-EHV

All-in-one type Compact PLC MICRO-EHV

Compact Body with great features

High Function model (MVH)

Standard model (MVL)



USB port for programming (MVH/MVL) Ethernet communication port (MVH)

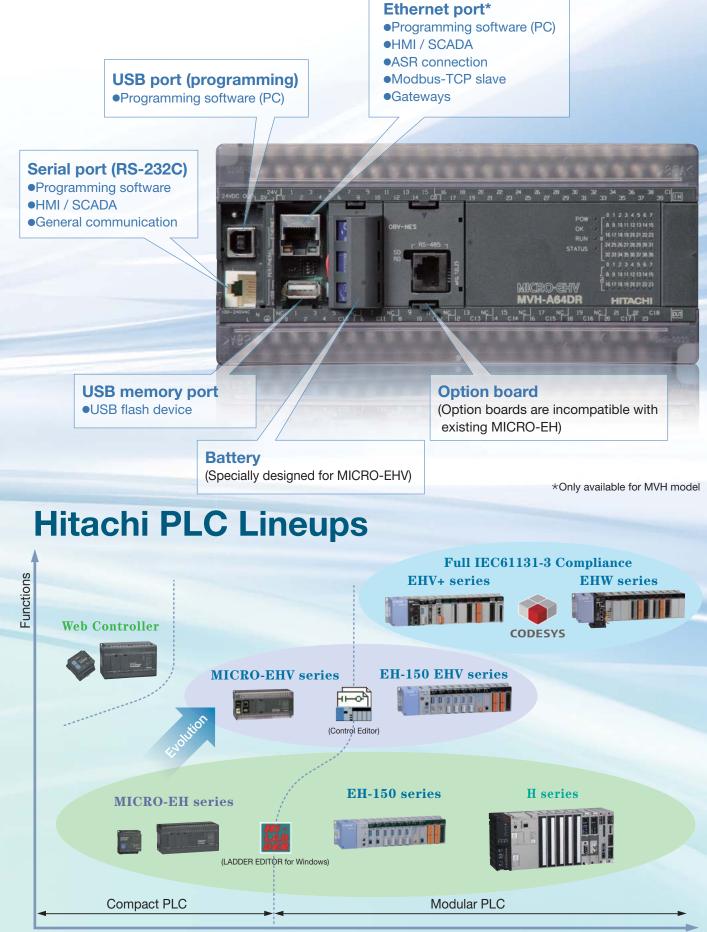
Program up/downloading from/to USB flash device (MVH) User program can be copied directly from/to USB flash device without PC.

Easy connection with Hitachi inverters (MVH/MVL) Easy connection, controlling and monitoring with Hitachi inverters NE-S1, WJ200 and SJ700.

Same programming software with EHV series (MVH/MVL) Control Editor ver.4 supports both MICRO-EHV and EHV series.

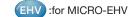
Control Editor - Master PLO	- Mas	terPLCO8	24Rev19	_sa - [Ma	ster_can	rier line]								
Elle Edit Yiew Online	Ico	Window	v Help				1.7							_ #
000000		00	22	X Ro C	1 25 1	2 6	m							
* 3-1 -1- # 101 101 -11	41	0.64	a ch c	- 65 - 64 ·	ai 0	n n i		$\tau = 1$	-4 at 1	- 1				
											00 13			
E A & & 4	8.84	का इस	S#t 2~	11 -		10 m	福台	200m 100	• 1	4				-
CPU parameters +	_	1 Y355	2 M2030	8	4	5	6	7	1.1		10	11	12 WED121.0	
CPU settings		1300			DM142	FL		15	-	-				[00101]
I IP address	187	CONV	INV(ML)1 NV(MP)		DM12A Auto N	FL		Auto PUN					ML INV2 speed	
Seriel communic				M5									WRD131.8	
Ethernet (task cc	188			Auto Run constant Speed									MR INV3 speed	
Colendar dock.	189	WJ206 Ma	dax 2000er x 1500660	an> 2Nm)	EH-4VH -	10+ 18V	-2040+	2047						(08102)
S Project pessword		M2000	M2010	M2011	MB								R7EC	[00103]
Parameter settings 1/0 Configuration	155	INVOIL) I NVOIL) I	OPE	Auto	Aute Pur							-	err clear	1
- M Retentive Area				M2012	M2017	M2015	ME				Re O	ide clear		
Unk parameters	191			duny	ML	Start	ML Ban				WM8	= WMS AND 108 = 0 109 = 0	D HC	1
Program	1000	M1500	M1501	M1502	M1503	M1507	M2019	M2002	M2009		_		Y300	[00104]
Master_corrier ir	192	master	alave err	master PLC err	slave PLI err	C enter loca	Ship	DOK	DOK			1	master CONV	1
master each	1	MB	WRDOGA	WRDDDDD	DIF								MB	[00105]
Master_unusual :	A	Andre Barr	Shaft.	Accelerat	11								Auto Pan	

MIGRO-EHV Series



I/O numbers







High Function model (MVH)

64-point type

(Input 40 points / Output 24 points)



40-point type

(Input 24 points / Output 16 points)



Standard model (MVL)

64-point type (Input 40 points / Output 24 points)



40-point type

(Input 24 points / Output 16 points)

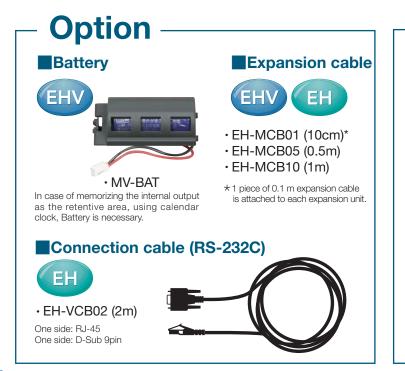


High Function model

Model	Spec
MVH-A64DR	AC power supply, DC input 40 points, Relay output 24 points
MVH-D64DR	DC power supply, DC input 40 points, Relay output 24 points
MVH-D64DT	DC power supply, DC input 40 points, Transistor output 24 points (sink)
MVH-D64DTPS	DC power supply, DC input 40 points, Transistor output 24 points (source)
WIVE-D04D1F3	(20 points with short-circuit protection)
MVH-A40DR	AC power supply, DC input 24 points, Relay output 16 points
MVH-D40DR	DC power supply, DC input 24 points, Relay input 16 points
MVH-D40DT	DC power supply, DC input 24 points, Transistor output 16 points (sink)
MVH-D40DTPS	DC power supply, DC input 24 points, Transistor output 16 points (source)
WWT-D40D1F3	(12 points with short-circuit protection)

Standard model

Model	Spec
MVL-A64DR	AC power supply, DC input 40 points, Relay output 24 points
MVL-D64DR	DC power supply, DC input 40 points, Relay output 24 points
MVL-D64DT	DC power supply, DC input 40 points, Transistor output 24 points (sink)
MVL-D64DTPS	DC power supply, DC input 40 points, Transistor output 24 points (source)
WIVL-D04D1F3	(20 points with short-circuit protection)
MVL-A40DR	AC power supply, DC input 24 points, Relay output 16 points
MVL-D40DR	DC power supply, DC input 24 points, Relay input 16 points
MVL-D40DT	DC power supply, DC input 24 points, Transistor output 16 points (sink)
MVL-D40DTPS	DC power supply, DC input 24 points, Transistor output 16 points (source)
WIVL-D40D1F3	(12 points with short-circuit protection)



Option board EHV

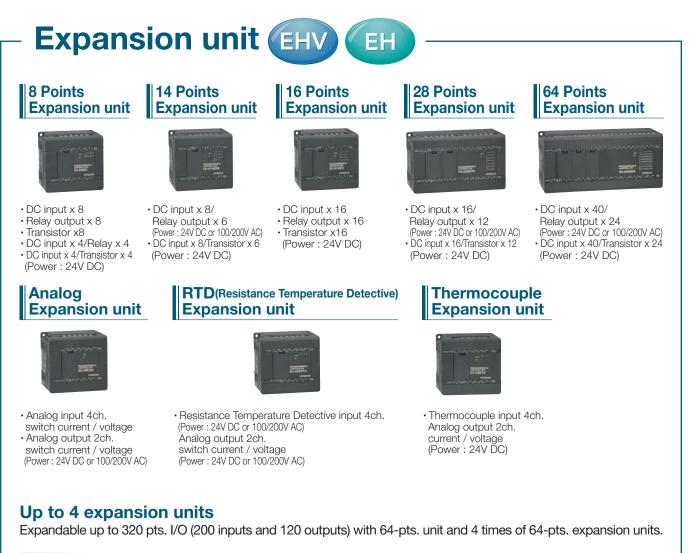


RS-485 (2-wire)



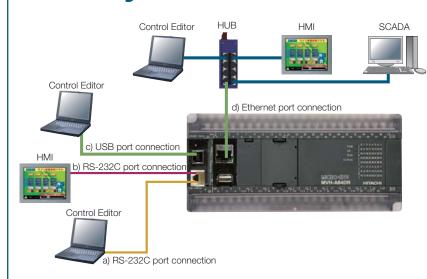
OBV-485A RS-485 (4-wire), 10bit Analog (voltage) input 2ch.

MIGRO-EHV Series



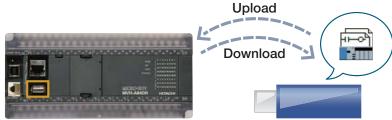


Variety of network connectivity



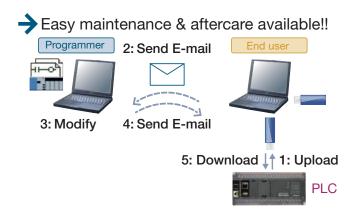
- a) Connection to Programming software (Control Editor) by RS-232C : EH-VCB02(2m)
- b) Connection to HMI by RS-232C : EH-VCB02(2m) a) or b) Either one
- c) Connection to Programming software (Control Editor) by USB : Please prepare the USB cable (A type - B type)
- d) Connection to Programming software (Control Editor), or HMI, or Personal computer : Please prepare the LAN cable (Straight) and HUB

FEATURE 1 Image: Model Program up/downloading from/to USB flash device (MVH) User program can be copied directly from/to USB flash device without PC.



Advantage of USB memory connection

If troubles happen and end-users do not have programming tool or are not familiar with PLC, user-program can be easily uploaded to usb flash device without PC and sent to experts over email.



FEATURE 2

Ethernet port (MVH model)

Configure-less Ethernet connection

MICRO-EHV can be easily connected with PC/devices which support Hitachi PLC protocol.

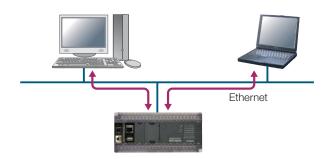


MVH MODEL



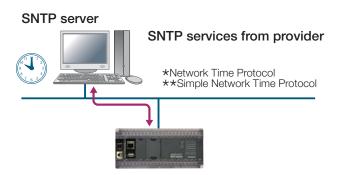
Ethernet ASR function

ASR stands for Automatic Sending & Receiving function. MICRO-EHV can send or receive data message with other PLC or PC in cyclic or event invoked.



NTP client function

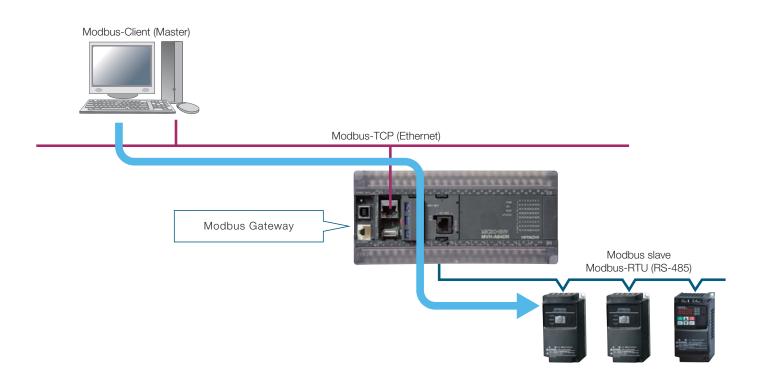
If NTP or SNTP server is in the network, time information can be read out with NTP/SNTP protocol.





Modbus Gataway function

"Modbus Gateway function" of MICRO-EHV is client (master) on Modbus-TCP network be able to communicate with the slave device on serial network (Modbus-RTU), through the MICRO-EHV.



FEATURE 3 MVH MVL

Easy connection with Hitachi's inverters and Oriental motor's stepper motor, Omron's temperature controller.

Easy connection with Hitachi's inverters, Oriental Motor's stepper motor and Omron's temperature controller in Modbus-RTU(RS-485), operation control and status monitoring can be able to easily. (Inverter, stepper motor, temperature controller are able be mixed in same communication line.)

MICRO-EHV have prepared communication command of each device, user be able to read and write data in the memory map image by directly specifying the internal output of the PLC from the ladder program, there is not required for communication program.



Connection only communication line to the slave device. It's "omit wiring" and "smart control".

(1) Inexpensive because it does not require a dedicated cable.

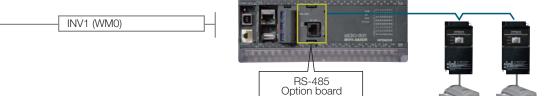
(2) Only wiring of communicate. Not require of I/O wiring to each slave .

(3) Possible to multiple remote control, and communicate up to 31 slave units, total communication length up to 500m*

 \star In case of combine with stepper motor by ORIENTAL MOTOR CORP., total communication length is up to 50m

Dedicated command of control and monitoring for Hitachi inverter.

Example



Applicable HITACHI inverter: SJ700, WJ200, NE-S1

"INV1" command is dedicated command of control and monitoring for Hitachi inverter. (Applicable HITACHI inverter : SJ-700, WJ200, NE-S1)

This command to be assign to communication area with PLC's internal output a total of 8 words (3 words to write, 5 words to read), in the ladder program. Through the set or reset of each bit or word of writing area be able to run / stop, forward rotation / reverse rotation and set to output frequency of the inverter. And be able to monitoring for output frequency value, output current, the other operating state and error of inverter in the reading area.

		F	Е	D	С	В	А	9	8	7	6	5	4	3	2	1	0
WM0	W	EXE	SJ	IT8	IT7	IT6	IT5	IT4	IT3	IT2	IT1	_	FQL	FQE	RST	REV	FWD
WM1	W							No	de addre	ss (0 to 2-	47)						
WM2	W						0	utput frec	luency se	t (0.01 to	400.00 H	lz)					
WM3	R	ERR	-	-	—	-	—	_	-	_	-	-	AL	ARF	RDY	DIR	RUN
WM4	R	-	-	MI8	MI7	MI6	MI5	MI4	MI3	MI2	MI1	MO6	MO5	MO4	MO3	MO2	MO1
WM5	R						Out	put freque	ency moni	tor (0.01	to 400.00) Hz)					
WM6	R						0	utput curr	ent monit	or (0.00 t	o 655.30	A)					
WM7	R							Con	nmunicati	on error c	ode						

Dedicated command of control and monitoring for Stepper motor.

Example





Applicable stepper motor : AR series, RKII series

"OMST1" command is dedicated command of control and monitoring for ORIENTAL MOTOR's stepper motor. (Applicable motor : AR series, RK-II series)

This command to be assign to communication area with PLC's internal output a total of 32 words (16 words to write, 16 words to read), in the ladder program.

Through the set or reset to positioning data (velocity, position, etc.) of each bit or word of writing area, be able to positioning.

And be able to monitoring for moving velocity value, current position, the other operating state and error of stepper motor in the reading area.

		F	Е	D	С	В	А	9	8	7	6	5	4	3	2	1	0
WM10	W	EXE	ECR	-	-	ALM	FBV	FBP	CV	CP	_	_	-	—	ALR	PV	PD
WM11	W							N	ode addre	ss (0~24	7)						
WM12	W	RVS	FWD	-JOG	+JOG	SSTART	MS2	MS1	MS0	_	FREE	STOP	HAME	START	M2	M1	MO
WM13	W							Positi	oning Nun	nber set () to 7						
WM14	W							Pos	sition set (l	_ower 16	oits)						
WM15	W							Pos	sition set (l	Jpper 16	oits)						
WM16	W							Velo	ocity set (l	ower 16	oits)						
WM17	W							Velo	ocity set (l		oits)						
WM18	W								Alarm	Reset							
WM19									unde	fined							
-WM1F									unue	lineu							
WM20	R	REX	ERR	-	-	RAL	RFV	RFP	RCV	RCP	-	-	-	-	RAR	RPV	RPD
WM21	R								mmunicati								
WM22	R				Comm	unication :	status (Le	east signif	icant bit is	0/1 inver	sion in ev	ery comn	nunication	n cycle)			
WM23	R								ication cy	cle time (l	Jnits: ms)						
WM24	R	TLC	END	MOVE	TIM	AREA3	AREA2			ALM	WNG	READY	HOME-P	STAR-R	M2-R	M1-R	M0-R
WM25	R								ng positior	````	,						
WM26	R								ng positior	<u> </u>	/						
WM27	R								ng velocity	1	,						
WM28	R								ng velocity	<u>\ </u>	/						
WM29	R							Feedba	ack positic	on (Lower	16bits)						
WM2A	R								ack positic	(1 1	/						
WM2B	R								ack veloci		/						
WM2C	R							Feedba	ack veloci	ty (Upper	16bits)						
WM2D	R							Ala	arm code (H00 to H	FF)						
WM2E -WM2F									unde	fined							

Dedicated command of control and monitoring for Temperature controller.

Example





"OCTP1" command is dedicated command of control and monitoring for OMRON's temperature controller. (Applicable temperature controller : E5CC, E5EC)

This command to be assign to communication area with PLC's internal output a total of 32 words (16 words to write, 16 words to read), in the ladder program.

Through the set or reset to control data (temperature, PID parameters, etc.) of each bit or word of writing area, be able to temperature control.

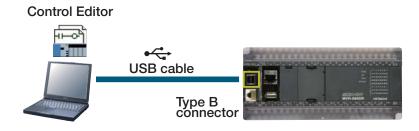
And be able to monitoring for current temperature value, heater current, the other operating state and error of communication in the reading area.

		F	E	D	С	В	A	9	8	7	6	5	4	3	2	1	0
WM30	W	EXE	ECR	_	C12	C11	C10	C9	C8	C7	C6	C5	C4	C3	C2	C1	CO
WM31	W							No	ode addre:	ss (0 to 2-	47)						
WM32	W							Ta	arget temp		set						
WM33	W								PID para								
WM34	W								PID para	0							
WM35	W								PID para	()							
WM36	W								Alar								
WM37	W								Jpper limit								
WM38	W							L	ower limit		1						
WM39	W								Alar								
WM3A	W								Jpper limit								
WM3B	W								ower limit								
WM3C	W								ater burno								
WM3D	W								PV input of								
WM3E	W							S	SP lump se	0	le						
WM3F									unde								
WM40	R				1		1	Cor	nmunicati	on error v	alue				1	1	
WM41	R	REX	ERR	_	—	-	—	-	-	-	-	-	-	-	-	-	STS
WM42	R								ication cy	,	,)					
WM43	R								oller statu:	`	,						
WM44	R								oller statu:	<u> </u>	/						
WM45	R								ller status		16bits)						
WM46	R								imal point								
WM47	R								Current te								
WM48	R								Setting ter		Э						
WM49	R								Heater								
WM4A	R							Οι	utput curre		ng)						
WM4B	R								unde	tined							

FEATURE 4 MVH MVL

USB communication port for programming software (Control Editor)

This is a maintenance port for programming software. Programming software can be used in the notebook without RS-232C serial port.

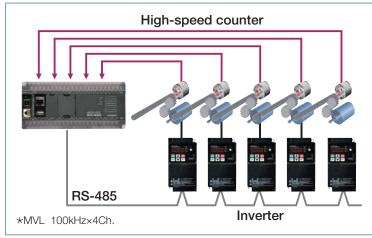


MIGRO-EHV Series

FEATURE 5 MVH MVL

High-speed counter input, Pulse train / PWM output.

5ch.* 100kHz high-speed counter



AC servo

WX20

WR0

3ch. 65kHz Pulse train / PWM output



Simple programming and plain command description.

Numerical substitution

The numerical substitution is described in a numerical formula and connected in "=".

It is not required to describe an exclusive command.

Arithmetic operation

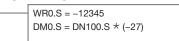
Addition, subtraction, multiplication, and division arithmetical operations (+, -, *, /) can be expressed by expression using every day. Plural arithmetic operations can be described in a processing box. Data handling is convenient, simply and proud.

Singed integer arithmetic operations, floating point arithmetic operations can be expressed equally. The visibility of the program can be improved.

Integer

WR0 = 12345 + WR1 WR0 = WN0 / 256





Floating point

WR0

WR10

WR20



= WR1 + WR2

= WR0 * WR4

= WR8 / WR6

WR0=WX20

The analog input/output is not require for both the special setting and command.

The analog input value is stored by applicable "WX".

The analog output value is outputted by substituting the analog value for applicable "WY".

Analog value can be treated without the special setting and command.

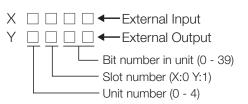


FEATURE 7 MVI MVI

Fixed address system to recognize a mounting position by I/O No.

Even if an input and output unit is changed, I/0 No. of other units is not influenced.

Because an implementation position from an input and output number is known, the change and maintenance of the ladder program is easy.



X0~X39 X1000~X1015 X2000~X2015 Input 64points Basic 16input 16input 16output 16output Y100~Y123 Y3016~Y3031 Y4016~Y4031 Output X0~X39 X1000~X1007 Input X2000~X2015 -"__".b" - " - "&" | m 1.1<u>.5</u>47.-.76-18 8output 64points Basic 8input 16input 16output HER. Y100~Y123 Y3016~Y3023 Y4016~Y4031 Output

Example of I/O No.



Removable terminal block in compatible with MICRO-EH

Adopted the removable terminal block compatible with MICRO-EH (40 points, 64 points type). So be able to replace MICRO-EH to MICRO-EHV without removing existing wiring.



FEATURE 9 MVH MVL

External I/O - refresh inhibiting function

Inhibiting external input - refresh

Regardless of an ON/OFF state of the external input signal (X/WX), can let external input data have ON with "set / reset function" of touch panel and Control Editor. This function is convenient for non-wired external inputs or a program check at the time of debugging. (The input LED of the unit does not turn on.)

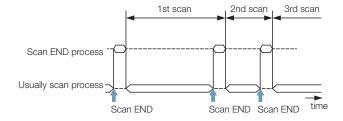
Inhibiting external output - refresh

When an external output data is let have ON with "set / reset function" of touch panel and Control Editor, its real external output signal is not reflected. Please use it for the cases that do not want to operate real external equipment at the time of debugging. (The output LED of the unit does not turn on.)

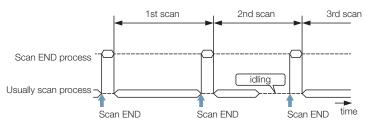
Constant scanning function

PLC repeats execution, external I/O process \rightarrow ladder program by external I/O process \rightarrow external I/O process \rightarrow . "Scan time" is one time that "execution takes by input-output process \rightarrow ladder program from beginning to end". By a state of the instruction execution / non-execution used in a program, "the scan thyme" changes. Therefore the timeliness that "input-output process" is carried out changes. After program execution, become the idling state to a set point of "the constant scan thyme" by using a "constant scan" function. As a result, "input-output process" comes to be always carried out in (e.g., in every 6msec) in the same period. Please use it for in replacement from a case to prevent you from influencing it by the increase and decrease of the program in response time and other PLC knowing the scan time.

Disabled Constant scan function (Usually)



Enabled Constant scan function



Set in "Operation parameters" window of the Control Editor

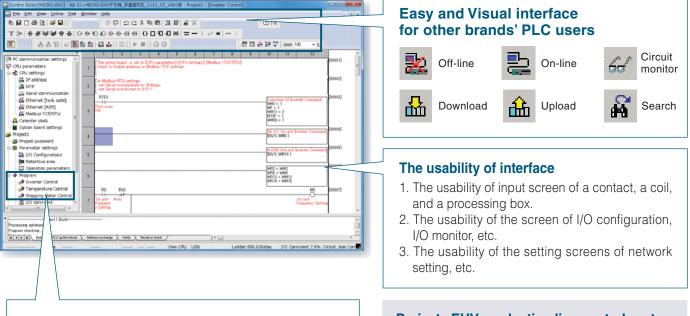
Operation Control	Operation Mode
📄 Enable RUN Input	I/O configuration Error STOP 👻
I/O address 🚽	Scan Time Error [Normal scan]
Max.Scan Time	Scan Time Error [Cyclic scan]
Setting Value 100 ms	Scan Time Error [Interrupt scan] STOP -
[1-65535ms]	Luncer of Luncer
	Constant scan
Digital Filter	📝 Enable constant scan
Setting Value 4 × 0.5ms	Setting value 6 ms

FEATURE 10 MVD MVD

The programming software is easy to use. "Control Editor"

The function which supports the improvement in efficiency of program development.

- Program sheet structure which makes easy management, appropriation, combination, and division of a program.
- The interface which employed the merit of Windows® software in the maximum efficiently and which is easy to use.

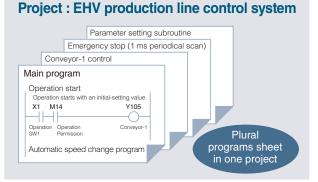


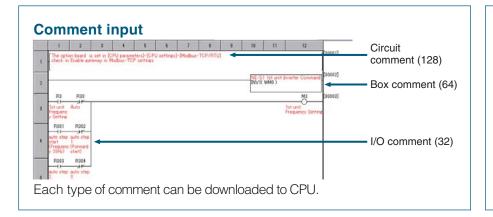
Program sheet structure

Multiple program sheets for multi-purpose and multi-programmers.

The ease of management, appropriation, combination, and division of a program.

Program sheet can be copied easily by right mouse click after opening multiple Control Editor.





Program convert tool

The Ladder program of MICRO-EH can be convert. Convertible for ladder program file to Control Editor with program convert tool.

Basic unit Specifications

	Ite	em		High Function model	Standard model	
I/O Lineups				40pts(Input 24pts,output 16pts)	40pts(Input 24pts,output 16pts	
1/0 Lineups				64pts(Input 40pts,output 24pts)	64pts(Input 40pts,output 24pts	
	Program memory			16k	steps	
	Comment memory		I/O comment	12	8kB	
Control			Box, Circuit comment)kB	
specifications	CPU			32-bit CIS	C processor	
opeenieuterie	Processing method				n cyclic method	
	Processing speed		Basic commands)µs ~	
			Substitution commands		μs ~	
Calculation processing	Basic commands				ypes	
specifications	Arithmetic / Application com	nands			types .	
	I/O processing method	Dania I CAmainta	E uropeanieur (4)		processing	
	External I/O points (64points	Basic +64 points	Expansion x4)	320 points (Input : 200 p		
External I/O specifications	Expansion	High Speed Cour	tor	100kHz×5 ch. (32bit)	4 units 100kHz×4 ch. (32bit)	
specifications	Special I/O	Pulse train outpu			×3 ch.	
	opecial 1/0	Interruption input		5 ch.	4 ch.	
		USB port (for pro			es	
		Serial port programming / HMI		Yes		
		(RS-232C)	General communication		es	
		USB memory por		Yes (USB 2.0)	-	
	built-in communication port		programming / HMI	Yes (TCP/IP)	_	
Communication			ASR communication	Yes	-	
specifications		Ethernet port	Modbus-TCP Slave	Yes	-	
			Modbus Gateway	Yes	_	
	Option board		programming / HMI	Y	es	
	communication port (RS-485)		ASR communication		es	
	(RS-232C coming soon)		Modbus-TCP Master		es	
	(;	- ()	Modbus-TCP Slave		es	
		R (bits)		· · ·	(R0 – R7BF)	
	Date memory	WR (Word)	ad also us d		- WR7FFF)	
	Timor (include counter 512 n	M/WM (Bit / wor	u snareu)	2,048 points (WM7FF) (2K)	
	Timer (include counter 512 p Counter	oints)		512 points (
		DIF (up)			points	
Internal output		DFN (down)			points	
specifications		Edge coil (up)			points	
	Edge detection	Edge coil (down)			points	
		Edge Processing	Box (up)		points	
		Edge Processing	(. ,		points	
	Clock function (*1)			Y	es	
	Retentive area (*1)			Y	es	
	Program method			Lac	dder	
Programming	Program seat			3	32	
specifications	constant scan				es	
	Refresh prohibition			Y	es	

*1 Battery is necessary

Product Specifications

Classification	Туре	Model Name		Specifica	tions	
olassinoation	Type		Power	Input	Output	Remarks
		MVH-A64DR	100/200 V AC	24V DC x 40	Relay x 24	
	High Function	MVH-D64DR	24V DC	24V DC x 40	Relay x 24	
	model	MVH-D64DT	24V DC	24V DC x 40	Transistor x 24	Sink
	lindudi	MVH-D64DTPS	24V DC	24V DC x 40	Transistor x 24	Souse
asic unit					(short circuit protection)	
4 Points		MVL-A64DR	100/200 V AC	24V DC x 40	Relay x 24	
	Standard	MVL-D64DR	24V DC	24V DC x 40	Relay x 24	
	model	MVL-D64DT	24V DC	24V DC x 40	Transistor x 24	Sink
		MVL-D64DTPS	24V DC	24V DC x 40	Transistor x 24	Souse
			100/200 \/ AC	241/ DC × 24	(short circuit protection)	
		MVH-A40DR	100/200 V AC 24V DC	24V DC x 24	Relay x 16	
	High Function	MVH-D40DR	24V DC 24V DC	24V DC x 24	Relay x 16 Transistor x 16	Sink
	model	MVH-D40DT	24V D0	24V DC x 24	Transistor x 16	SIIIK
asic unit		MVH-D40DTPS	24V DC	24V DC x 24	(short circuit protection)	Souse
0 Points		MVL-A40DR	100/200 V AC	24V DC x 24	Relay x 16	
or onno		MVL-D40DR	24V DC	24V DC x 24	Relay x 16	
	Standard	MVL-D40DT	24V DC	24V DC x 24	Transistor x 16	Sink
	model				Transistor x 16	
		MVL-D40DTPS	24V DC	24V DC x 24	(short circuit protection)	Souse
		EH-D8ED	24V DC	24V DC x 8	_	
		EH-D8ER	24V DC	_	Relay x 8	
		EH-D8ETPS	2411 DC		Transistor x 8	Souse
xpansion units		EU-DOFILO	24V DC		(short circuit protection)	Souse
Points		EH-D8ET	24V DC	-	Transistor x 8	Sink
FUILIS		EH-D8EDR	24V DC	24V DC x 4	Relay x 4	
		EH-D8EDTPS	24V DC	24V DC x 4	Transistor x 8	Souse
			240 00		(short circuit protection)	
		EH-D8EDT	24V DC	24V DC x 4	Transistor x 4	Sink
		EH-D14EDT	24V DC	24V DC x 8	Transistor x 6	Sink
		EH-D14EDTP	24V DC	24V DC x 8	Transistor x 6	Souse
xpansion units		EH-D14EDTPS	24V DC	24V DC x 8	Transistor x 6	Souse
4 Points					(short circuit protection)	00000
		EH-D14EDR	24V DC	24V DC x 8	Relay x 6	
		EH-A14EDR	100/200 V AC	24V DC x 8	Relay x 6	
		EH-D16ED	24V DC	24V DC x 16	_	
xpansion units		EH-D16ER	24V DC	_	Relay x 16	
6 Points		EH-D16ETPS	24V DC	_	Transistor x 16	Souse
					(short circuit protection)	0.1
		EH-D16ET	24V DC	-	Transistor x 16	Sink
		EH-D28EDT	24V DC	24V DC x 16	Transistor x 12	Sink Souse
xpansion units		EH-D28EDTP	24V DC	24V DC x 16	Transistor x 12 Transistor x 12	30056
8 Points		EH-D28EDTPS	24V DC	24V DC x 16	(short circuit protection)	
01 UIIIta		EH-D28EDR	24V DC	24V DC x 16	Relay x 12	
		EH-A28EDR	100/200 V AC	24V DC x 16	Relay x 12	
		EH-A64EDR	100/200 V AC	24V DC x 40	Relay x 24	
		EH-D64EDR	24V DC	24V DC x 40	Relay x 24	
xpansion units		EH-D64EDT	24V DC	24V DC x 40	Transistor x 24	Sink
4 Points					Transistor x 24	
		EH-D64EDTPS	24V DC	24V DC x 40	(short circuit protection)	Souse
	0	EH-D6EAN	24V DC	Analog x 4	Analog x 2	
nalog Expansion unit	5	EH-A6EAN	100/200 V AC	Analog x 4	Analog x 2	
		EH-A6ERTD	100/200 V AC	RTD4 x 4	Analog x 2	
TD Expansion units		EH-A4ERTD	100/200 V AC	RTD4 x 4	-	
Le Expansion units		EH-D6ERTD	24V DC	RTD4 x 4	Analog x 2	
		EH-D4ERTD	24V DC	RTD4 x 4	-	
hermocouple		EH-D6ETC	24V DC	Thermocouple x 4	Analog x 2	
pansion unit		EH-D4ETC	24V DC	Thermocouple x 4	-	
		EH-MCB10		xpansion cable for Expansion unit (1	/	
xpansion cable		EH-MCB05		kpansion cable for Expansion unit (5	,	
		EH-MCB01	E	kpansion cable for Expansion unit (1		
ption board		OBV-NES		RS-485 (2-wire) serial option boa	rd	
		0BV-485A), 10bit Analog (Voltage) input 2ch.		
ithium battery		MV-BAT		r data memory back-up (for MICRO		
rogramming software	е	EH-CTE-E	Progr	amming software (for EHV-CPU/MIC control editor for Windows [®] 7/XP		
onnection cable		EH-VCB02		on between MICRO-EHV and a perso		

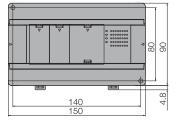
1 piece of 0.1 m expansion cable is attached to each expansion unit *Please prepare the USB cable (A type - B type) *Windows is a registered trademark of Microsoft Corp. in the U.S. and other countries.

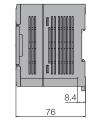
General Specifications

	Item	Specif	ication
Power supply ty	/pe	AC	DC
Power voltage		100/110/120 V AC (50/60 Hz), 200/220/240 V AC (50/60 Hz)	24 V DC
Allowable volta	ge range	85 to 264 V AC wide range	19.2 to 30 V DC
Hold-up		10 ms at 85 to 100 V AC, 20 ms at 100 to 264 V AC	10 ms at 19.2 to 30 V DC
	Operating ambient temperature	0 to 5	55 °C
	Storage ambient temperature	-10 to	
Physical	Operating ambient humidity	5 to 95 % RH (n	
environment	Storage ambient humidity	5 to 95 % RH (n	o condensation)
environment	Pollution degree	Pollution degree	
	Usage environment	No corrosive gases. Not stained with	n organic solvents, No excessive dirt
	Altitude/Atmospheric pressure	Altitude 2,000m max. (Trans	sport condition: 70kPa min.)
Mechanical operation	Vibration resistance	Complies with J Constant Half amplitude : 0.15mm (vibration 10 to 57Hz) 10 times each in X.	, Constant acceleration : 19.6m/s ² (vibration 57 to 150Hz)
condition	Shock resistance	Complies with JIS	S C 60068-2-27.
	SHOCK TESISLATICE	147 m/s ² , 11ms, 3 times	s in X, Y, and Z directions
	Electrostatic discharge immunity	Complies with IEC61000-4-2 ±4kV C	Contact discharge, ±8kV Air discharge
Electrical	Radiated electromagnetic field	Complies with IEC61000-4-	3 10V/m (80 to 1,000MHz)
operation	Noise resistance	Noise voltage 1,500 Vpp Noise pulse width 100 ns, 1 µs (noise sim Based on NEMA ICS 3-304 Static noise: 3,000 V at metal exposed area Complies with EN50081-2 and EN50082-2	ulator to power terminals)
Insulation resist	tance	20 MΩ or more between the AC external ter	minal and the protection earth (PE) terminal
Withstand volta	ge	1,500 V AC for one minute between the AC extern	nal terminal and the protection earth (PE) terminal
Grounding		Class D dedica	ated grounding
Structure		Panel-mount	ed type, IP30
Installation	Direction	Vert	ical
Installation	Mounting	Screws (M4) or [DIN rail mounting
Cooling		Natural a	ir cooling

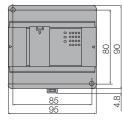
Dimensions

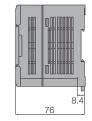
40-point type basic unit



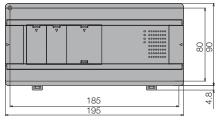


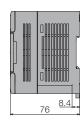
8/14/16-point expansion unit, Analog Expansion unit Thermocouple expansion unit , RTD expansion unit



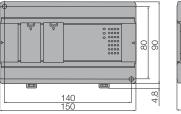


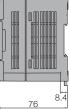
64-point type basic unit , 68-point expansion unit





28-point expansion unit





[Unit : mm]

MEMO

MIGDO-ELW Gorboo
MIGRO-EHV Series



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